

## 5.8. Mixed Strategies for Zero-Sum Games and The Minimax Theorem.

### 5.8.1. Definition.

A bimatrix game with matrices  $A$  and  $B$  is called a zero-sum game, if  $A = -B$ .

Hence everything that was said about bimatrix games in general makes sense for zero-sum games. Especially, there are mixed strategies, and a pair of mixed strategies  $(p_e, q_e)$  is a point of equilibrium, if

$$\forall (\vec{p} \in \Delta_{m-1}) (\vec{p}^T A \vec{q}_e \leq \vec{p}_e^T A \vec{q}_e)$$

$$\forall (\vec{q} \in \Delta_{n-1}) (\vec{p}_e^T B \vec{q} \leq \vec{p}_e^T B \vec{q}_e)$$

Since  $A = -B$ , these conditions reduce to

$$\forall (\vec{p} \in \Delta_{m-1}) (\vec{p}^T A \vec{q}_e \leq \vec{p}_e^T A \vec{q}_e)$$

$$\forall (\vec{q} \in \Delta_{n-1}) (\vec{p}_e^T A \vec{q} \geq \vec{p}_e^T A \vec{q}_e)$$

These two inequalities are equivalent to

$$\forall (\vec{p} \in \Delta_{m-1}, \vec{q} \in \Delta_{n-1}) (\vec{p}^T A \vec{q}_e \leq \vec{p}_e^T A \vec{q}_e \leq \vec{p}_e^T A \vec{q})$$

### 5.8.2. Definition.

Let  $G$  be a zero-sum game with matrix  $A$ . A pair of mixed strategies  $(p_s, q_s)$  is called a saddle point, if

$$\vec{p}^T A \vec{q}_s \leq \vec{p}_s^T A \vec{q}_s \leq \vec{p}_s^T A \vec{q}$$

holds for all  $\vec{p} \in \Delta_{m-1}$  and all  $\vec{q} \in \Delta_{n-1}$ .

The following statement is obvious:

### 5.8.3. Proposition.

Every point of equilibrium of a zero-sum game is a saddle point, and vice versa, every saddle point is a point of equilibrium.

We know from Nash's theorem that every zero-sum game has at least one point of equilibrium consisting of mixed strategies. Since every point of equilibrium is a saddle point, we obtain.

**5.8.4. Theorem (John von Neumann, 1928)**

*Let  $G$  be a zero-sum game with matrix  $A$ . Then  $G$  has a saddle point.*

We can rewrite this condition for a point of equilibrium in the following form:

**5.8.5. Theorem.**

*Let  $G$  be a zero-sum game with matrix  $A$ , and let  $(\bar{p}_s, \bar{q}_s)$  be a saddle point consisting of mixed strategies. Then*

$$\begin{aligned}\bar{p}_s^T A \bar{q}_s &= \max \{ \bar{p}^T A \bar{q}_s : \bar{p} \in \Delta_{m-1} \} \\ &= \min \{ \bar{p}_s^T A \bar{q} : \bar{q} \in \Delta_{n-1} \}\end{aligned}$$

*Moreover, in this case*

$$\begin{aligned}\bar{p}_s^T A \bar{q}_s &= \min \{ \max \{ \bar{p}^T A \bar{q} : \bar{p} \in \Delta_{m-1} \} : \bar{q} \in \Delta_{n-1} \} \\ &= \max \{ \min \{ \bar{p}^T A \bar{q} : \bar{q} \in \Delta_{n-1} \} : \bar{p} \in \Delta_{m-1} \}\end{aligned}$$

**Proof.** We only have to verify the second part of the theorem. First, we show that for every choice of sets  $X$  and  $Y$  and every function  $\omega : X \times Y \rightarrow \mathfrak{R} \cup \{\pm\infty\}$  we have

$$\max \{ \min \{ \omega(x, y) : y \in Y \} : x \in X \} \leq \min \{ \max \{ \omega(x, y) : x \in X \} : y \in Y \}$$

Indeed, if  $x_0 \in X$  and  $y_0 \in Y$  are given, then

$$\min \{ \omega(x_0, y) : y \in Y \} \leq \omega(x_0, y_0) \leq \max \{ \omega(x, y_0) : x \in X \}$$

Since this holds for each value of  $x_0 \in X$ , we conclude that

$$\max \{ \min \{ \omega(x_0, y) : y \in Y \} : x_0 \in X \} \leq \max \{ \omega(x, y_0) : x \in X \}$$

Again, this holds for every value of  $y_0 \in Y$ , hence

$$\max \{ \min \{ \omega(x_0, y) : y \in Y \} : x_0 \in X \} \leq \min \{ \max \{ \omega(x, y_0) : x \in X \} : y_0 \in Y \}$$

To complete the proof, we have to verify that for every saddle point  $(\bar{p}_s, \bar{q}_s)$  the inequality

$$\min \{ \max \{ \bar{p}^T A \bar{q} : \bar{p} \in \Delta_{m-1} \} : \bar{q} \in \Delta_{n-1} \} \leq \bar{p}_s^T A \bar{q}_s \leq \max \{ \min \{ \bar{p}^T A \bar{q} : \bar{q} \in \Delta_{n-1} \} : \bar{p} \in \Delta_{m-1} \}$$

holds. First, note that

$$\begin{aligned}\bar{p}_s^T A \bar{q}_s &= \max \{ \bar{p}^T A \bar{q}_s : \bar{p} \in \Delta_{m-1} \} \\ &= \min \{ \bar{p}_s^T A \bar{q} : \bar{q} \in \Delta_{n-1} \}\end{aligned}$$

Hence

$$\begin{aligned} \min \left\{ \max \left\{ \bar{p}^T A \bar{q} : \bar{p} \in \Delta_{m-1} \right\} : \bar{q} \in \Delta_{n-1} \right\} &\leq \max \left\{ \bar{p}^T A \bar{q}_s : \bar{p} \in \Delta_{m-s} \right\} \\ &= \bar{p}_s^T A \bar{q}_s \\ &= \min \left\{ \bar{p}_s^T A \bar{q} : \bar{q} \in \Delta_{n-1} \right\} \\ &\leq \max \left\{ \min \left\{ \bar{p}^T A \bar{q} : \bar{q} \in \Delta_{n-1} \right\} : \bar{p} \in \Delta_{m-1} \right\} \end{aligned}$$

This completes the proof.

Another popular version of John von Neumann's theorem is the following corollary:

### 5.8.6. Corollary.

*If  $G$  is a zero-sum game with matrix  $A$ , then*

$$\min \left\{ \max \left\{ \bar{p}^T A \bar{q} : \bar{p} \in \Delta_m \right\} : \bar{q} \in \Delta_n \right\} = \max \left\{ \min \left\{ \bar{p}^T A \bar{q} : \bar{q} \in \Delta_n \right\} : \bar{p} \in \Delta_m \right\}$$

### 5.8.7. Definition.

*If  $G$  is a zero-sum game with matrix  $A$ , then the value of  $G$  is defined as*

$$\begin{aligned} v(G) &= \min \left\{ \max \left\{ \bar{p}^T A \bar{q} : \bar{p} \in \Delta_m \right\} : \bar{q} \in \Delta_n \right\} \\ &= \max \left\{ \min \left\{ \bar{p}^T A \bar{q} : \bar{q} \in \Delta_n \right\} : \bar{p} \in \Delta_m \right\} \end{aligned}$$

### 5.8.8. Proposition.

*If  $G$  is a zero-sum game with matrix  $A$ , then for every saddle point  $(\bar{p}_s, \bar{q}_s)$  of mixed strategies we have*

$$v(G) = \bar{p}_s^T A \bar{q}_s$$

Conversely, if  $(\bar{p}, \bar{q})$  is a pair of mixed strategies, then the equation  $v(G) = \bar{p}^T A \bar{q}$  does not imply that  $(\bar{p}, \bar{q})$  is a saddle point. For example, if

$$A = \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}$$

then  $((1,0),(0,1))$  is a saddle point, hence the value of the game is 1. However, if  $(\bar{p}, \bar{q}) = ((0,1),(0,1))$ , then we also have

$$(0,1)A \begin{pmatrix} 1 \\ 0 \end{pmatrix} = 1$$

even though  $((0,1),(0,1))$  is not a saddle point.

Saddle points are easy to find using derivatives. If  $\vec{p} = (p_1, \dots, p_m)$  and  $\vec{q} = (q_1, \dots, q_n)$ , and if

$$\omega(p_1, \dots, p_m, q_1, \dots, q_n) = (p_1, \dots, p_m) A \begin{pmatrix} q_1 \\ \vdots \\ q_n \end{pmatrix}$$

then, for fixed values of the  $q_j$ 's, the function  $\omega$  has a maximum at  $\vec{p}_s$ , and for fixed values of the  $p_i$ 's, the function  $\omega$  has a minimum at  $\vec{q}_s$ . Hence the derivatives of  $\omega$  with respect to the  $p_i$ 's and  $q_j$ 's has to be 0. We have to be a bit careful, since the coordinates of  $\vec{p}$  and  $\vec{q}$  are constrained by the condition that the sum of their coordinates is equal to 1. Therefore the domain of  $\omega$  is not an open subset of Euclidean space, and boundary points usually deserve extra attention. This is best explained by an example:

**Example.** Find all saddle points of the game “Rock, Paper, Scissors”.

The matrix of this game is given by

$$A = \begin{pmatrix} 0 & 1 & -1 \\ -1 & 0 & 1 \\ 1 & -1 & 0 \end{pmatrix}$$

So the function  $\omega$  is given by

$$\omega(p_1, p_2, p_3, q_1, q_2, q_3) = p_1q_2 - p_1q_3 - p_2q_1 + p_2q_3 + p_3q_1 - p_3q_2$$

We can replace  $p_3$  by  $1 - p_1 - p_2$  and  $q_3$  by  $1 - q_1 - q_2$  and obtain

$$\omega^*(p_1, p_2, q_1, q_2) = p_2 - p_1 + q_1 - q_2 + 3p_1q_2 - 3p_2q_1$$

The domain of this new function is

$$\{(p_1, p_2, q_1, q_2) : 0 \leq p_1, p_2, q_1, q_2, 1 - p_1 - p_2, 1 - q_1 - q_2\}$$

The interior of this set is found by using just strict inequalities. Saddle points in the interior are found by taking derivatives:

$$\frac{\partial \omega^*}{\partial p_1} = -1 + 3q_2 = 0$$

$$\frac{\partial \omega^*}{\partial p_2} = 1 - 3q_1 = 0$$

$$\frac{\partial \omega^*}{\partial q_1} = 1 - 3p_2 = 0$$

$$\frac{\partial \omega^*}{\partial q_2} = -1 + 3p_1 = 0$$

Hence the only saddle point in the interior is given by  $\vec{p}_s = \vec{q}_s = \left(\frac{1}{3}, \frac{1}{3}, \frac{1}{3}\right)$ .

In order to find saddle points on the boundary, we have to use the method of Lagrange multipliers. We will skip this here.